



Operation	Output	Dictionary
insert(5,A)	(5 <i>.A</i>)	(5.A)
insert(7, <i>B</i>)	(7 <i>,B</i>)	(5,A),(7,B)
insert(2,C)	(2,C)	(5,A),(7,B),(2,C)
insert(8,D)	(8 <i>,D</i>)	(5,A),(7,B),(2,C),(8,D)
insert(2 <i>,E</i>)	(2 <i>,E</i>)	(5,A),(7,B),(2,C),(8,D),(2,E)
find(7)	(7 <i>,B</i>)	(5,A),(7,B),(2,C),(8,D),(2,E)
find(4)	null	(5, <i>A</i>),(7, <i>B</i>),(2, <i>C</i>),(8, <i>D</i>),(2, <i>E</i>)
find(2)	(2,C)	(5, <i>A</i>),(7, <i>B</i>),(2, <i>C</i>),(8, <i>D</i>),(2, <i>E</i>)
findAll(2)	(2 <i>,C</i>),(2 <i>,E</i>)	(5,A),(7,B),(2,C),(8,D),(2,E)
size()	5	(5,A),(7,B),(2,C),(8,D),(2,E)
remove(find(5))	(5,A)	(7,B),(2,C),(8,D),(2,E)
find(5)	null	(7,B),(2,C),(8,D),(2,E)



The findAll(k) Algorithm



The insert and remove Methods

Ψ			
Algorithm insert	t(<i>k, v</i>):		
Input: A key k a	nd value v		
Output: The ent	ry (k, v) added to D		
Create a new ent	ry e = (k, v)		
SinsertLast(e)	{ <i>S</i> is unordered}		
return e	(
Algorithm romo	vo(a):		
	ve(<i>e</i>).		
Input: All entry			
Output: The ren	hoved entry <i>e</i> or null if <i>e</i> was not in <i>D</i>		
{We don't assum	e here that e stores its location in 5}		
B = S.positions()			
while B.hasNext	() do		
p = B.next()			
if p.element() = e then		
, S.remo	ve(n)		
return			
roturn null	(there is no entry ain 0)		
return nun			
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Search Table

	 We store the items of the dictionary in an array-based sequence, sorted by key 	
	 We use an external comparator for the keys 	
۲	Performance:	
	find takes O(log n) time, using binary search	
	• insert takes $O(n)$ time since in the worst case we have to shift $n/2$ items to make room for the new item	
	 remove takes O(n) time since in the worst case we have to shift n/2 items to compact the items after the removal 	
۲	A search table is effective only for dictionaries of small size or for dictionaries on which searches are the most common operations, while insertions and removals are rarely performe (e.g., credit card authorizations)	